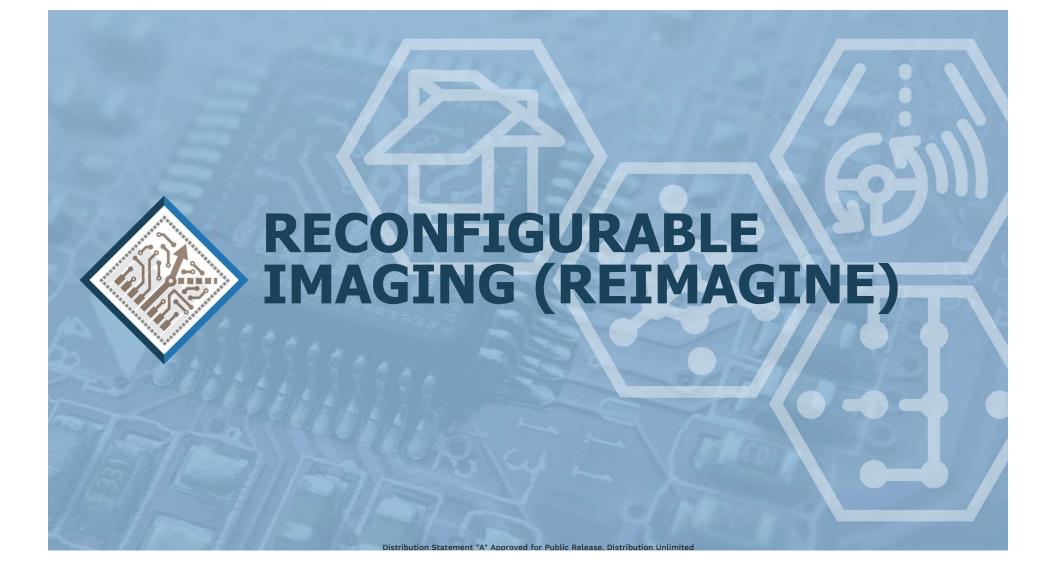




WHITNEY MASON

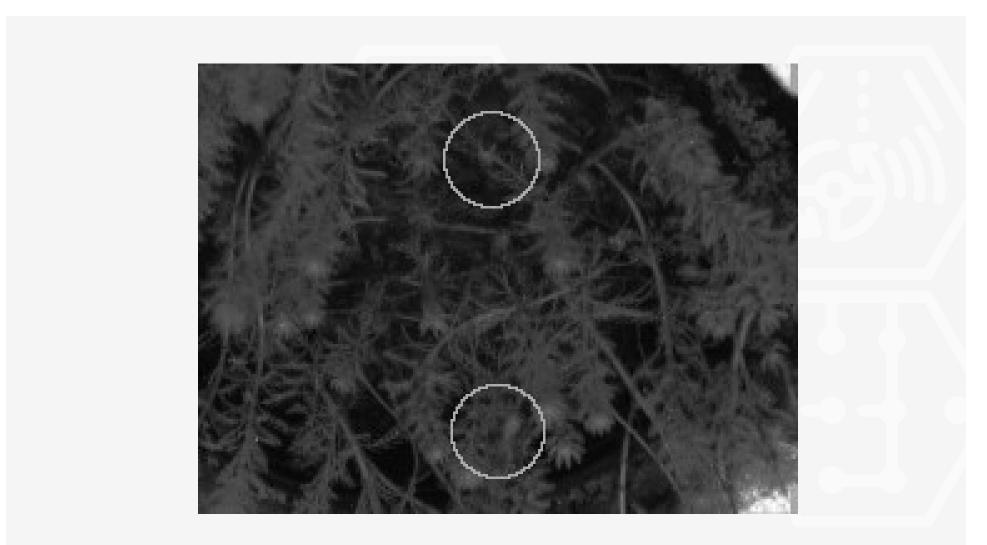
PROGRAM MANAGER DARPA MTO

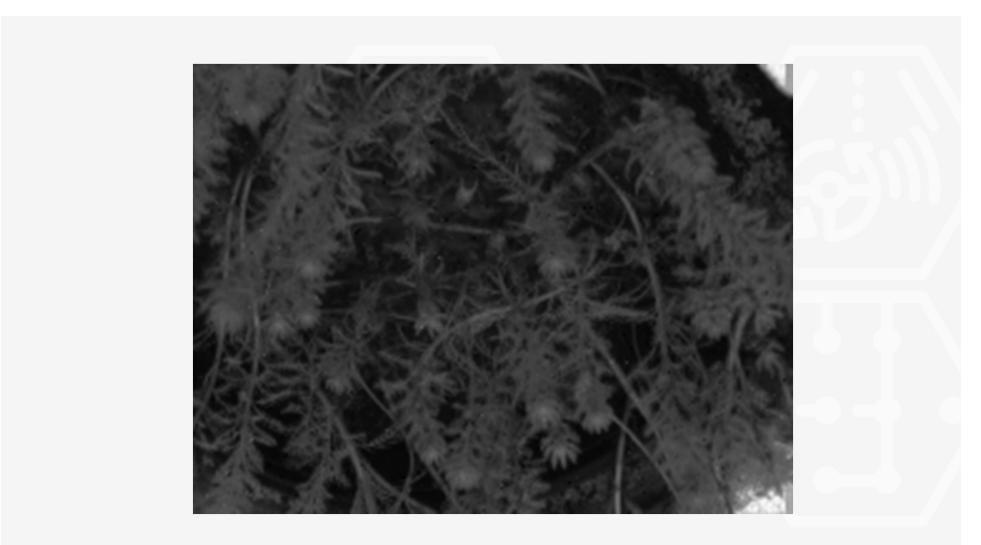


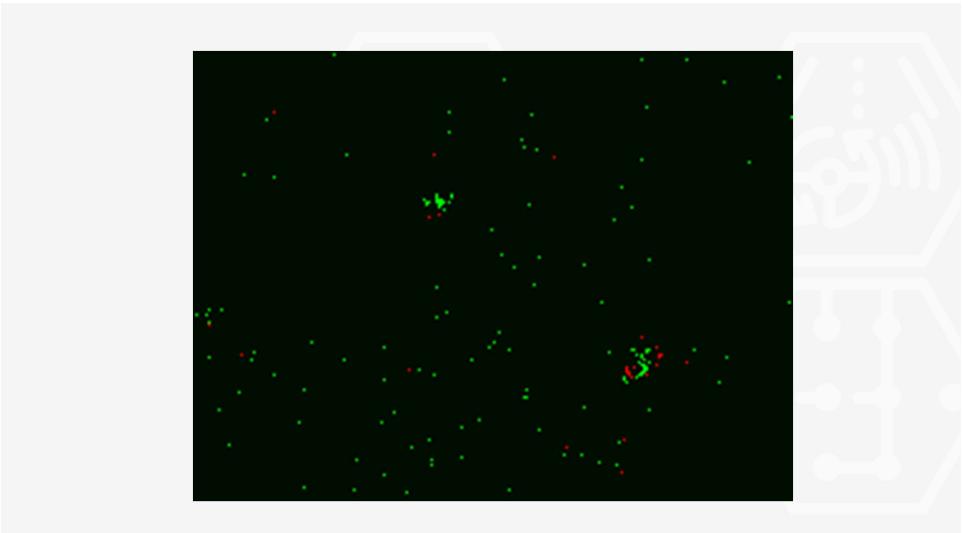
WHAT IS RECONFIGURABLE IMAGING?

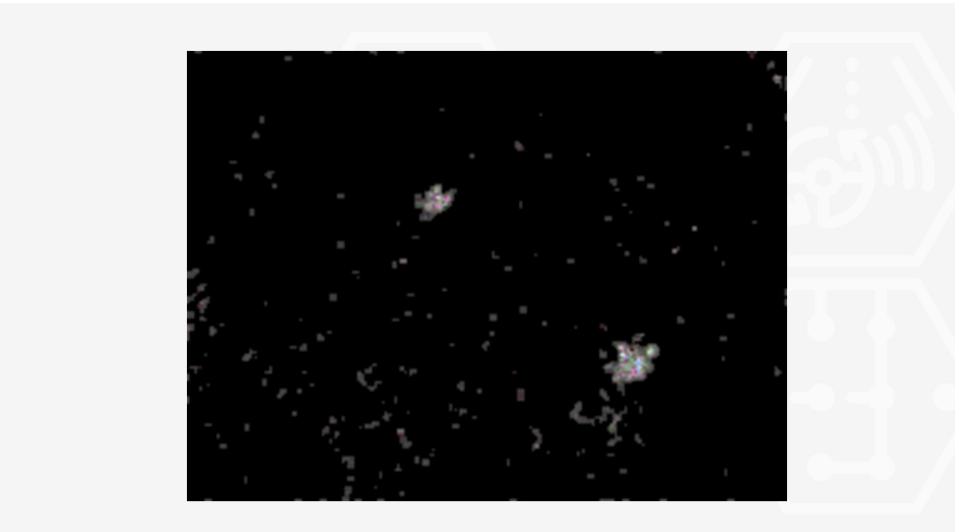
LET'S TAKE A LOOK AT A TYPICAL VIDEO, THEN DISSECT IT FOR RELEVANT INFORMATION

ERI



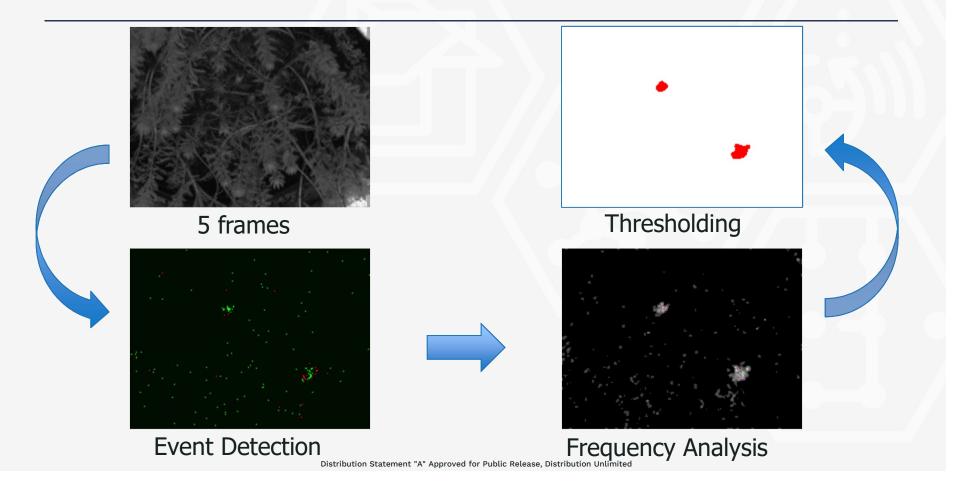








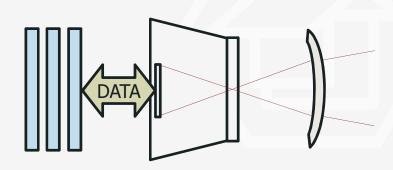
ANALYZING THE VIDEO



HOW DOES THE HARDWARE DIFFER?

ERI

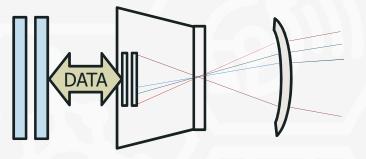
OPTICAL SENSOR HARDWARE



Processing

Image Capture

- Focal planes provide predetermined outputs
- Electronics perform all image processing



Processing

Image Capture & Processing

- Move some of the processing into the focal plane
 - Focal plane can adapt its outputs based on the scenario
 - Can save power and bandwidth

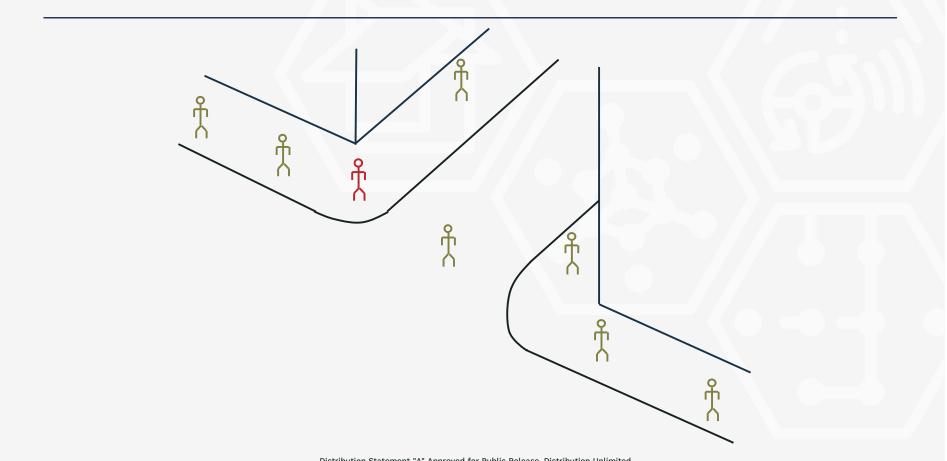
Adding field programmability to the focal plane allows adaptive and flexible imaging modes to meet a variety of sensor needs

SENSOR SOFTWARE POSSIBILITIES

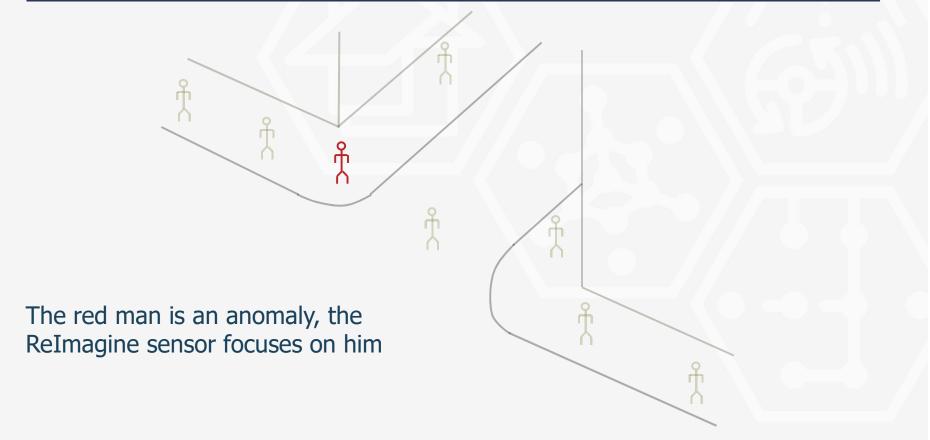
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MIMIC NEUROLOGICAL ANALYSIS OF AN IMAGE

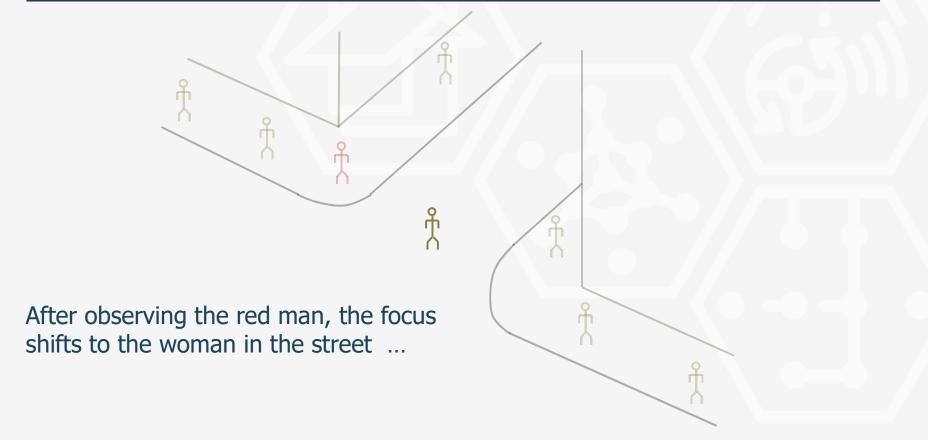
A TYPICAL SCENE



REIMAGINE SENSOR SOFTWARE



REIMAGINE SENSOR SOFTWARE



REIMAGINE SENSOR SOFTWARE



REIMAGINE

- Adds processing to the focal plane
 - Allows a single sensor to provide a variety of outputs
 - Field programmability based on the application and software
- Processing in the external electronics
 - Supports software to dynamically evaluate the scene
 - Determine where the information lies in the image
 - Reconfigures the focal plane to provide that information
- By focusing on information, the sensor can
 - Reduce output bandwidth
 - Accelerate decision making



ERI ELECTRONICS RESURGENCE INITIATIVE

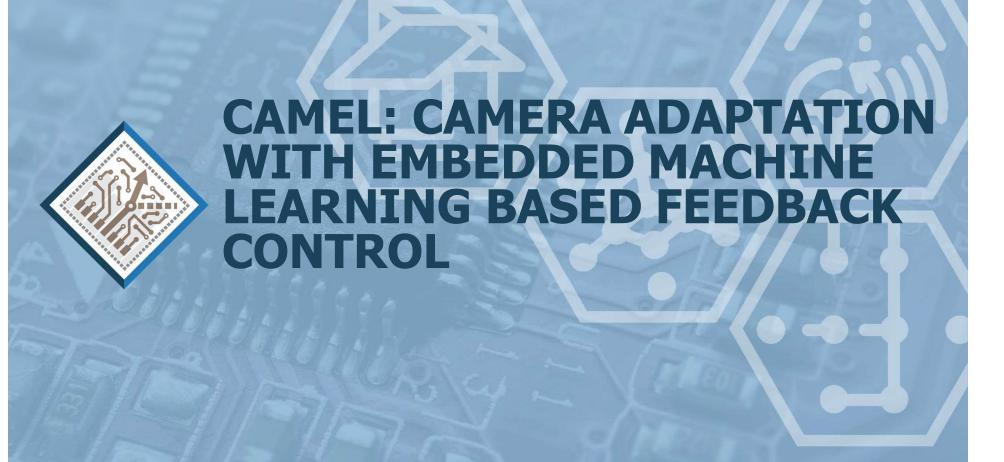
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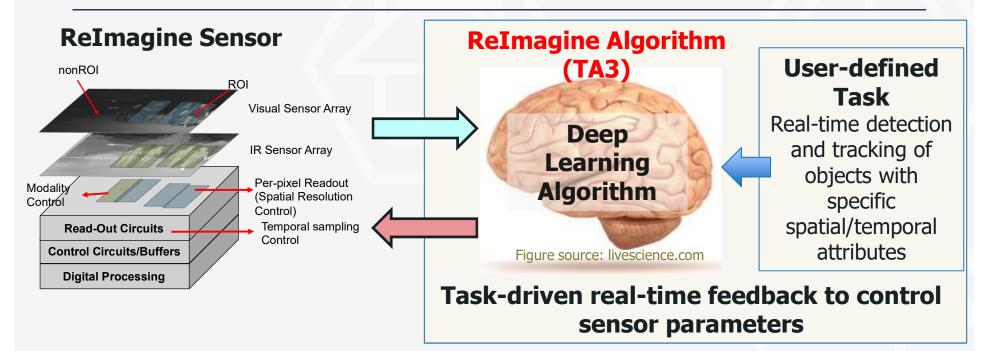


SAIBAL MUKHOPADHYAY

GEORGIA INSTITUTE OF TECHNOLOGY

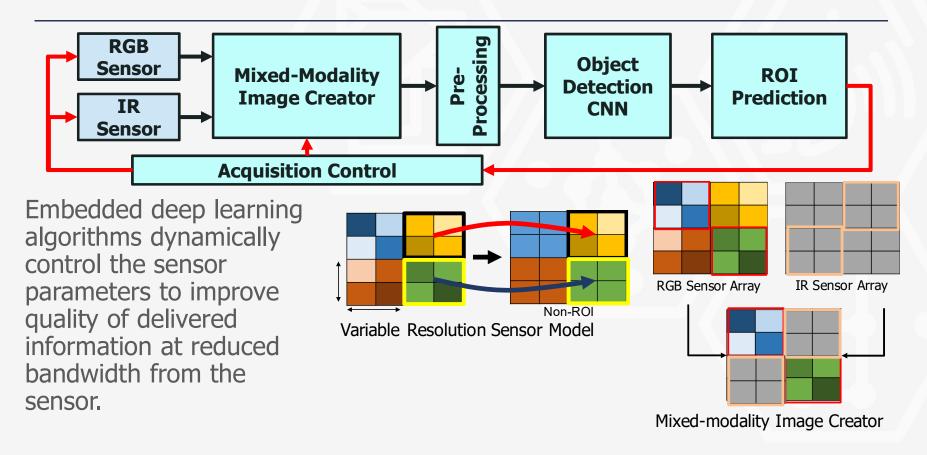


CAMEL: A CAMERA WITH BRAIN

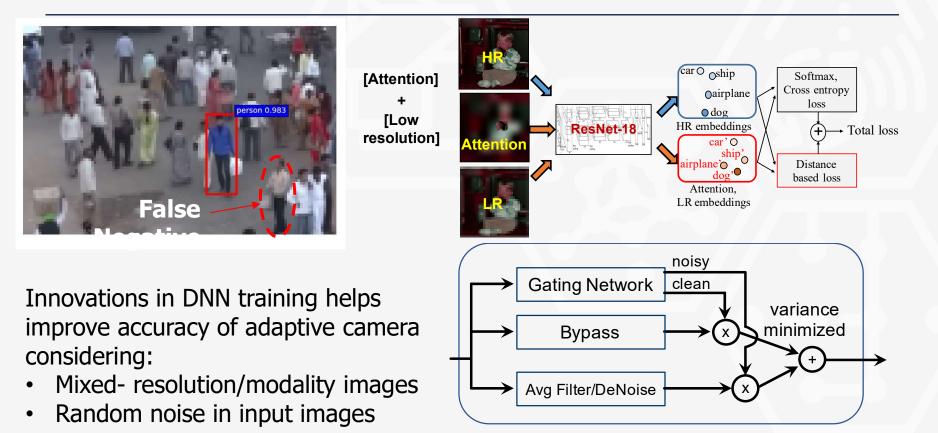


A camera that autonomously controls sensor parameters to increase information content in the picture or video by embedding deep learning algorithms in the processing layer.

EMBEDDED MACHINE LEARNING IN THE FEEDBACK LOOP



TRAINING DEEP LEARNING FOR FEEDBACK SYSTEM



Noise-robust design with mixture of pre-processing engines

RESULTS: MORE INFORMATION AT LESS BANDWIDTH

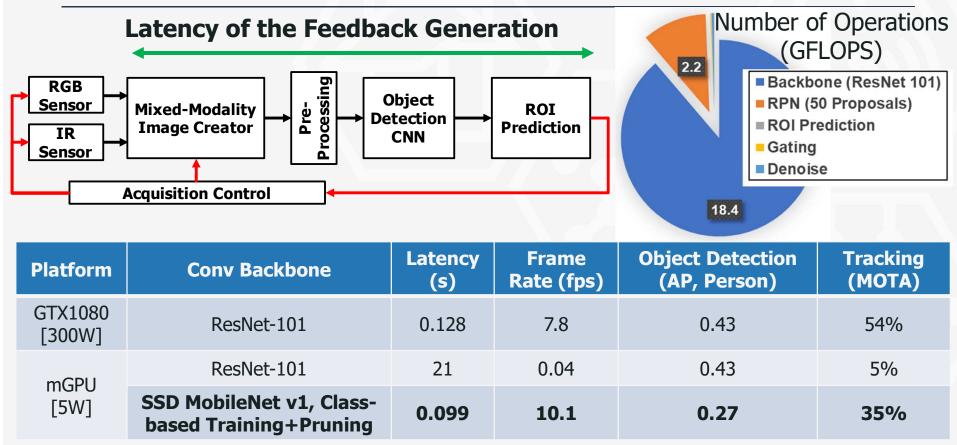




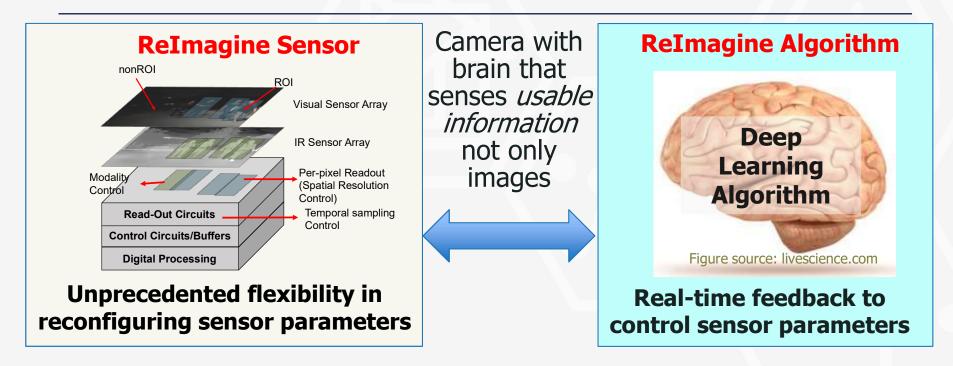
Detection maintained despite illumination variance

	Tracking Accuracy	Bandwidth (Normalized)
Baseline	0.528	1
CAMEL	0.650	4X Lower

CHALLENGE: FEEDBACK LATENCY



CONCLUSIONS



Collaboration with ERI will help in software-hardware co-design to enable complex algorithms within the resource-constrained camera platform



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